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## **Module 2: SOP Of Using Drone**

### **Session 6:**

#### **\* Power-on Checks**

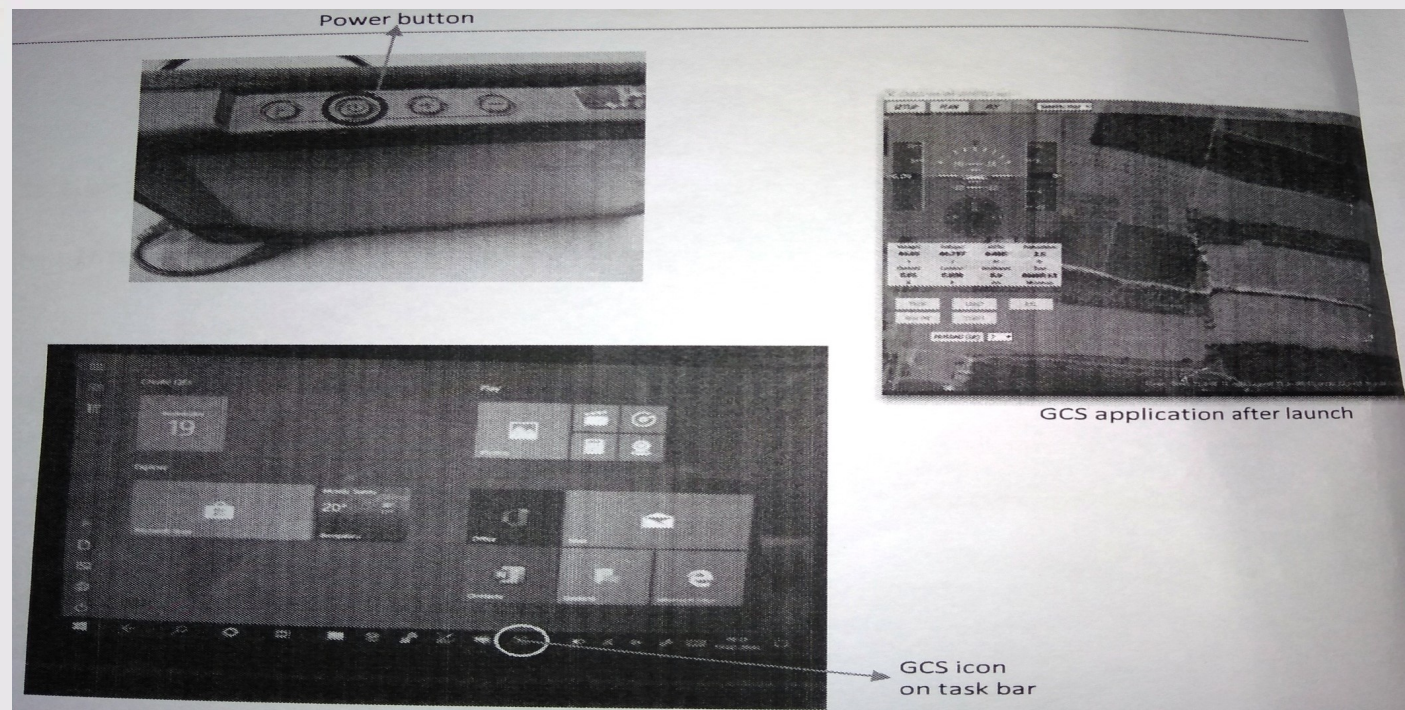


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# Power-on Checks

## Step-1: GCS setup

- power-on GCS tablet by pressing the power button on top tablet as shown

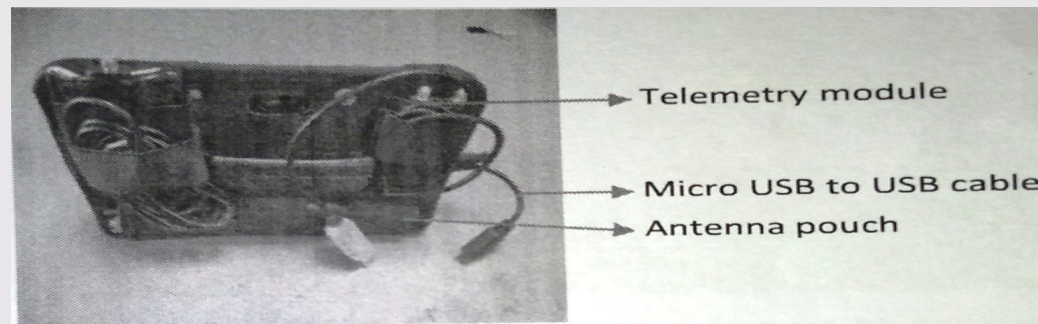




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## Step-2: GCS and GDT connections

- Take-out GDT antenna's and connect them to GDT module provided in the back pouch of GCS tablet.



Antenna connection



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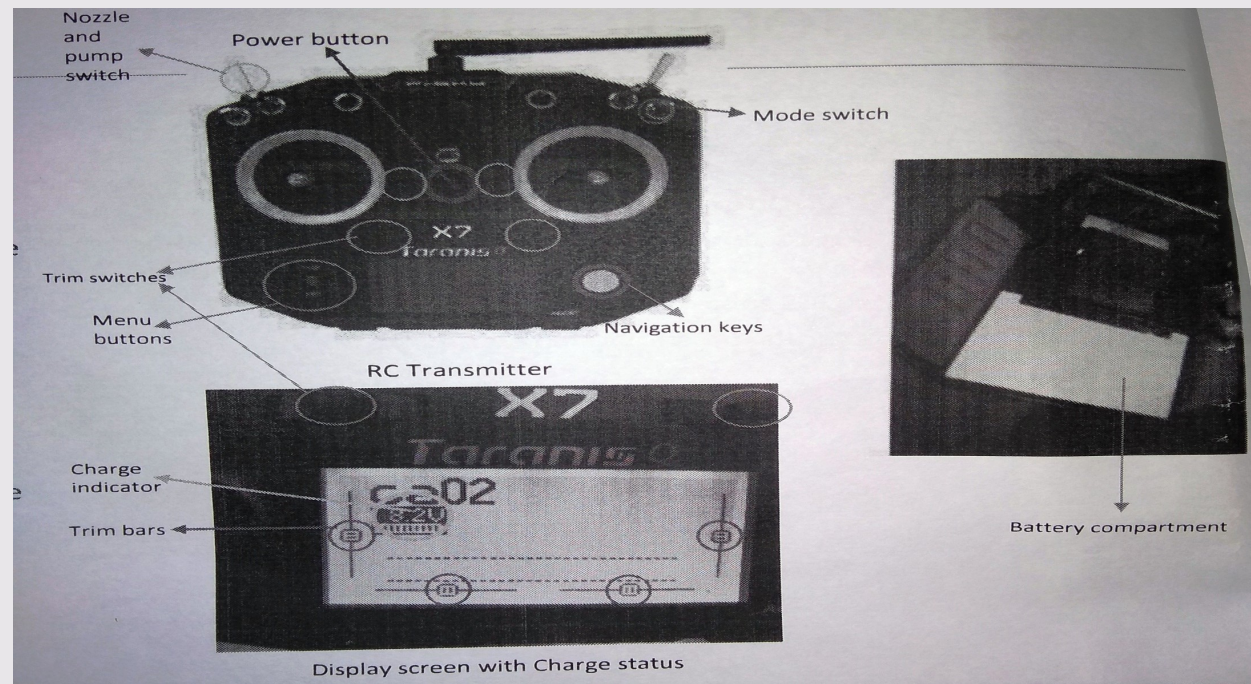
- Connect GDT to GCS tablet using the USB cable provided
- GDT side connections are shown in the figure



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## Step-3: Power-on RC Transmitter

- Power-on RC transmitter by pressing the power button once





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- Ensure the trim buttons are centered as shown in the figure
- If not centered use the trim switches of the corresponding channels to center it.
- Mode switch is the small switch on the top right corner
- Payload controlled via long switch on the top left corner I Battery is placed at the back in the compartment provided
- Navigational keys are on the top facing on either side of the display.



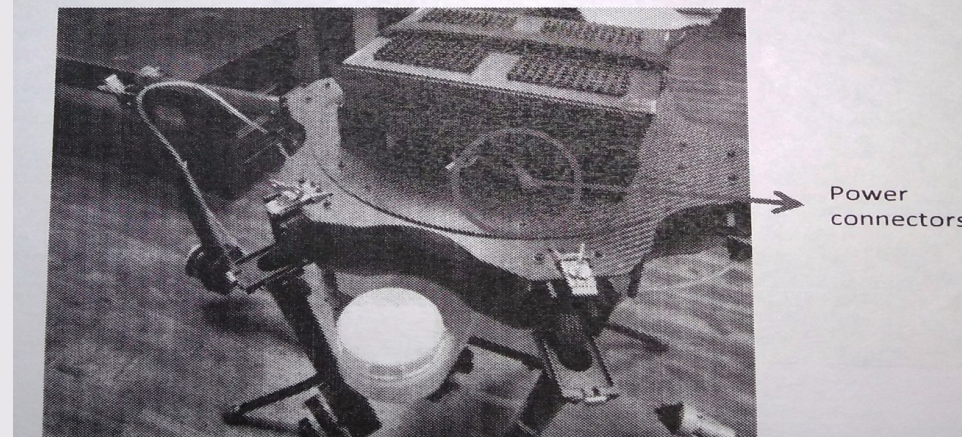
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## Step-4: Battery health check and mounting

- As shown in the product overview document check the battery voltage and percentage



Capacity checker





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- Battery voltage should be  $> 24.5 \text{ V}$  and  $>96\%$
- Place the battery with heat sinks facing top in the slots provided on the top plate
- Battery power outlet cables should be facing the rear of the RPAS and towards the RPAS power connectors

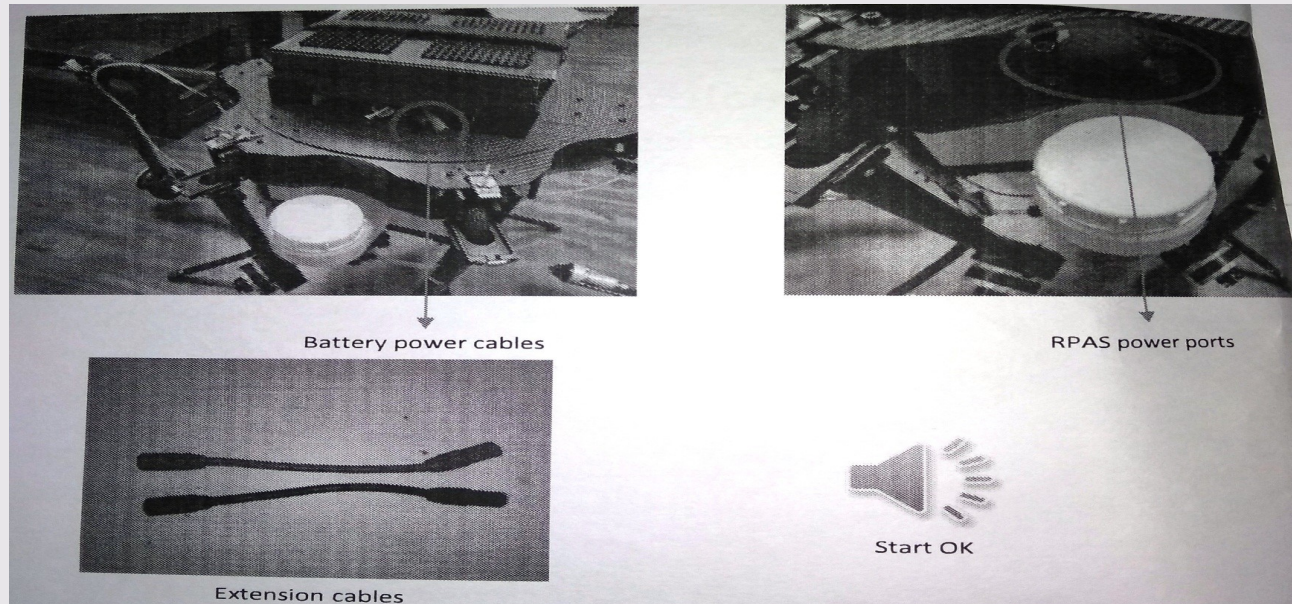




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## Step-5: powering RPAS

- Connect the battery power cables to RPAS power input ports using the extension cables (**BLACK** first and **RED** next)



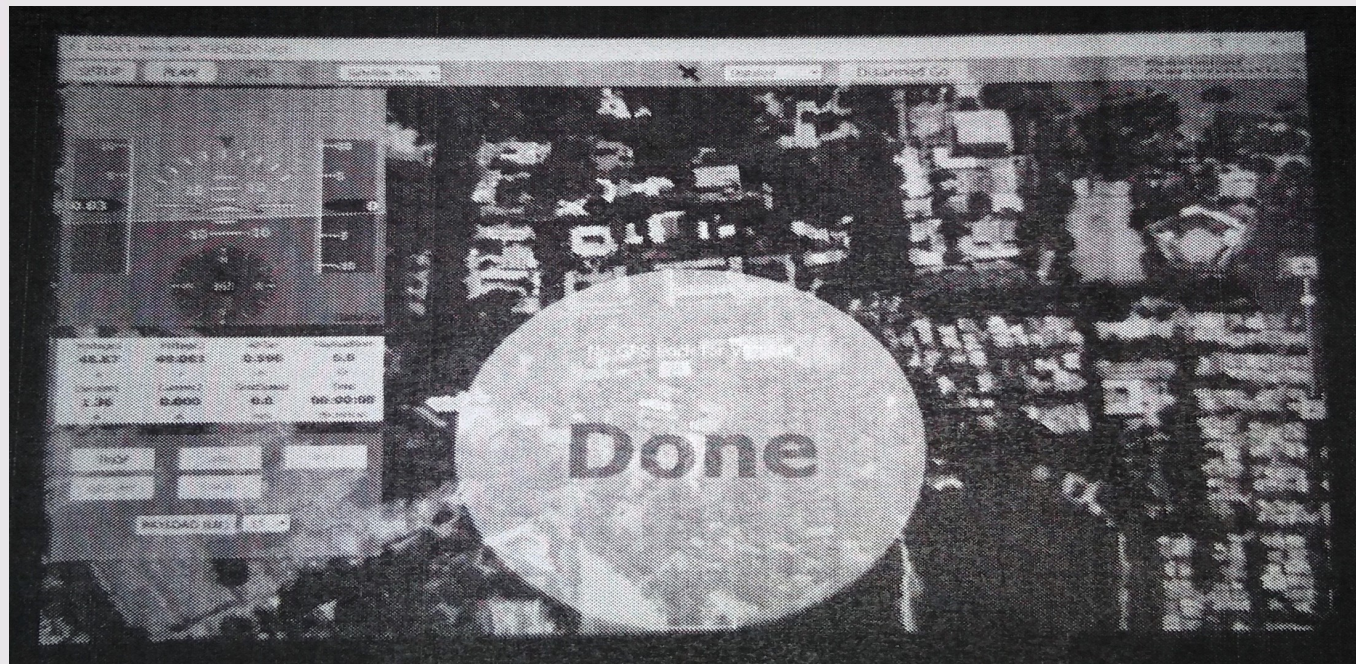
- Wait for RPAS to initialize (will hear a tone)
- Tone indicates "Start OK"



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## Step-6: Communication setup

- Upon launching GA-GCS application, connecting GDT to GCS tablet and powering RPAS





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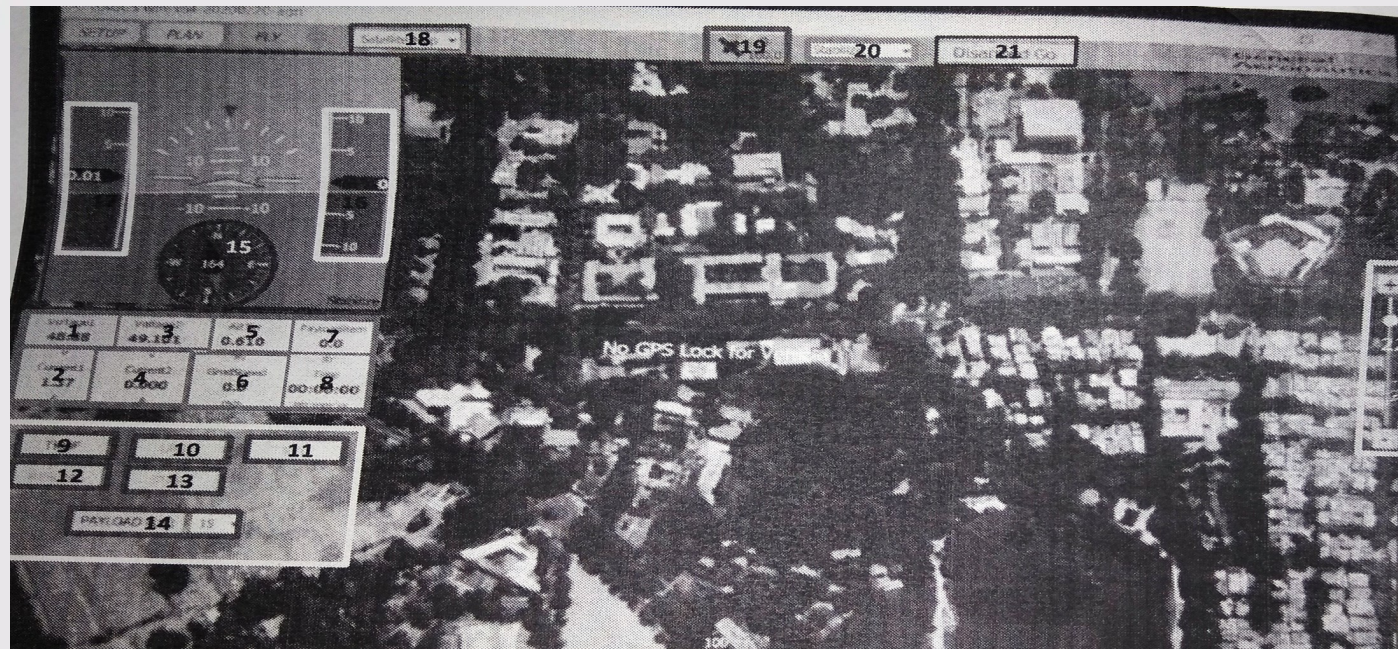
- RPAS will automatically connect to GCS through the telemetry
- Once after connection established Telemetry data will start to appear in the GCS screen as shown in the figure
- DONE will be displayed as the RPAS establishes communication with GCS



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## Step-7: Parameter and mode checks

- Check the following parameters are updated
- Flight Mode (current flight mode will be displayed, flight modes explained in the next slide)





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- Voltage and current (battery voltage should be similar to voltage checked with capacity checker)
- Terrain altitude( altitude information from the Terrain RADAR sensor is displayed here)
- Heading dial (heading data from the compass will be displayed here)
- Rem. Payload (update the payload from the dropdown provided at the bottom of the parameter section, should reflect in the Rem. Payload parameter tab) 11

Satellite count and hdop -

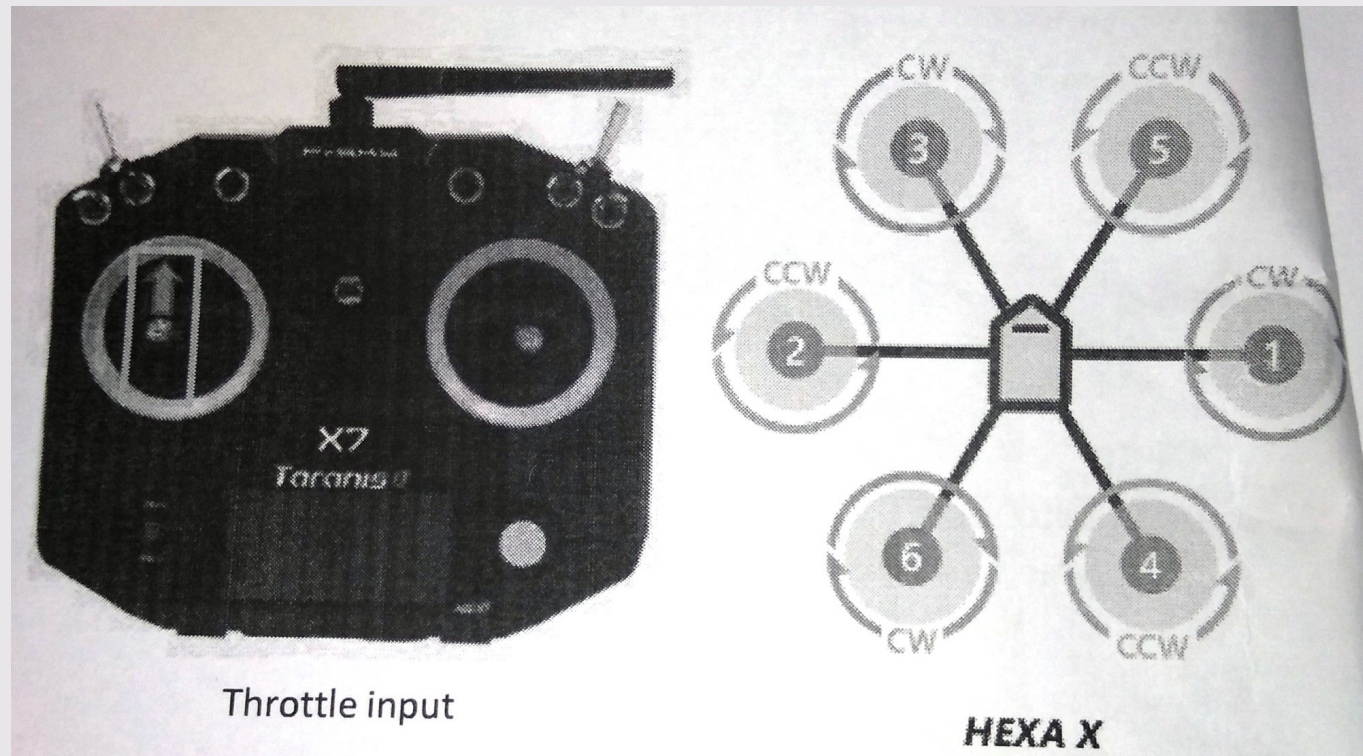
- Sats -  $>16$  (when powered-on indoors, this will be 0)
- Hdop  $<1$  (when powered-on indoors, this will be 100)



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## STEP – 8: Motor checks

- Long press the safty switch button provided on the GPS module until the RED light becomes solid





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- Take the RC transmitter
- Now arm the vehicle by holding the throttle stick to the right bottom corner at least for 5sec in the RC transmitter.
- A long tone can be heard indicating the RPAS is armed
- Now move the throttle stick above center position for the motors to start spinning.(move the throttle stick above zero position after arming, otherwise the RPAS will disarm automatically)
- Ensure all the motors are spinning
- Now hold the throttle stick to left bottom corner for 5 sec to disarm RPAS
- If any of the motors is not spinning, refer to the user manual



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## Step- 9 : disconnecting and packing

- Disconnect the battery connections ( RED first and BLACK next)
- Power-off RC transmitter
- Disconnect GDT connection from GCS tablet, close the application and close the tablet
- Remove the battery from RPAS and keep in storage place.





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**Thank you...**